OPERATING INSTRUCTIONS NIR - Absorption Sensor





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1 General information

The operating instructions enable the safe and efficient handling of the sensors EXcell 231 and EXcell 241.

The operating instructions belong to the product and must be stored in its direct vicinity and easily accessible to the staff at all times. Before starting any work, the staff must read these operating instructions carefully and understand them.

If these operating instructions incorporate documentation from suppliers (as an attachment), Exner Process Equipment assumes no guarantee for its contents, individual statements, technical data, etc.

1.1 Manufacturer

Exner Process Equipment GmbH Carl-Metz-Str. 26 D-76275 Ettlingen

1.2 Depiction of information

For simplified and safe work with these operating instructions, uniform safety instructions and symbols are used.

Safety instructions

Safety instructions protect against injury to persons and damage to property. The measures described for averting danger must be adhered to.

The safety instructions are structured as follows:



1 General information

The components have the following meaning:

- Signal word: marks the seriousness of the danger
- Warning sign: draws attention to the danger
- Type and source of the danger: names the causes of the danger
- Consequences: describes the consequences in case of non-observation
- Measures: provides measures to avert the danger

DANGER



This warning message marks a danger with a high risk which results in death or severe injury if not avoided.

WARNING



This warning message marks a danger with a moderate risk which can result in death or severe injury if not avoided.

ATTENTION



This warning message marks a danger with a low risk which can result in minor or moderate injury if not avoided.

NOTE

This note contains information regarding possible material or environmental damages which do not result in injury to persons.

Symbols

Marks	Meaning
»	Instruction with no specified sequence
1.	Instruction with a specified sequence
•	List
\rightarrow	Reference to Chapter
	Operating element, Push button, Button
✓	Result

2 Safety and protection measures

2.1 General safety instructions

The EXcell sensor is designed in such a way that no risks can arise from using the product if the operating instructions are observed.

- Read the operating instructions first.
- Only install or operate the sensor after having read and understood all notes on its safe and proper use.
- Keep the operating instructions in a safe place in order to be able consult them at all times if required.
- Only use the sensor and its accessories if they are in good order and condition.
- Ensure proper use of the sensor. Do not use it for applications for which it is not intended (e.g. as a step).
- Observe the laws, ordinances, regulations and standards applicable in the country of use and at the place of use.

2.2 Intended use

The EXcell sensor is attached to tanks or pipes. The optical part of the sensor is immersed into the process liquid in order to measure its physical properties through absorption of irradiated light.

- Prepare a maintenance schedule for the respective process.
- Only perform maintenance work described in these operating instructions!
- Changes to the sensor may only be carried out after consulting with the manufacturer.

NOTE

The manufacturer is not liable for damages arising from improper or unintended use.

2.3 Danger zones and residual dangers

Sensors are connected to tanks and pipes which can be pressurised. Process liquid can only escape in case of negligent action or improper use. The system or part thereof should therefore be depressurised and emptied completely before the sensor is removed.

- Before commissioning and after each maintenance, ensure that all seals and connections are complete and functional.
- Take appropriate safety precautions before touching the sensor as parts of it can adopt the process temperature.

2.4 Equipment and accessories

Only use tested and approved equipment and accessories.

Seals

The EXcell 231 / 241 sensor requires an elastomer seal. If you connect the sensor to your process using an adapter, then

- Choose material properties of the process and O-ring seals depending on the process medium and cleaning liquid.
- Take the swelling capacity and acid or base resistance of the sealing material into account.

2.5 Requirements of the staff

Qualification

Only trained professionals may install and service the sensor!

Protective clothing

When commissioning or servicing, the operating staff must wear goggles and appropriate protective clothing.

Accident prevention regulations (UVV)

Please observe the valid rules and regulations concerning occupational safety in the country and place of use!

2.6 Pictograms

For better orientation, pictograms and symbols are used in the operating instructions.



3 Technical data

3.1 Standards

The following standards were applied when manufacturing the sensor:

- EN 61326-1: 2013-7
- EN 61326-2-3: 2013-7
- DIN/EN 27027 (ISO 7027)

3.2 Specification

Sensor specifications	
Measurement range	06 AU; 06600 EBC; 012 OD
Resolution	0.01 AU
Accuracy	± 1%
Reproducibility	\leq 1 % of the final value
Wave length	850 nm
Light source	LED
Material	Stainless steel 1.4435 (316L)
Surface finish	Ra <0.37 μm
Measuring window	Sapphire
Process connection	Thread PG 13.5; union nut (G 1 ¼")
Process temperature	090 °C, autoclavable
Process pressure	Max. 16 bar (232 psi)
Electrical connection	Fischer Core series
Connector cable length	2 m / 5 m
Interfaces	RS485 Modbus, USB (with ECI-01), 0/420 mA with switching output (with ECI-03), 0/420 mA with zeroing function (configuration "DA")

Max. measuring range:

11	Optical path length								
Unit	5 mm	10 mm	20 mm						
AU	06	06	06						
OD	012	06	03						
EBC	06600	03300	01650						

3.3 Dimensions





Fig. 1: EXcell 231 / 241 dimensions

3.4 Environmental conditions

Ambient temperature -10...70 °C

Transport and storage temperature -20...80 °C

3.5 EXcell process conditions

Max. permissible pressure PS:	16 bar	
Max. permissible temperature TS:	90 °C	
Max. permissible sterilisation temperature	135 °C	max. 1 hour



Figure 2: Pressure - temperature diagram EXcell

3.6 Identification plate



Fig. 3: Identification plate (based on EXcell 231)

4 Product description

NOTE

The sensors of the EXcell series have an integrated temperature sensor. This is only used to monitor the condition of the sensor and is not suitable for precise control of the process temperature.

4.1 NIR – EXcell absorption sensor

4.1.1 Components



1	Fischer Core series
	connector plug
2	PG 13.5 thread
3	Measuring window

Fig. 4: EXcell 231 sensor

4.1.2 EXcell 231

The NIR absorption sensor EXcell 231 is a high-precision digital NIR rod sensor for monitoring production processes in the biotech, food and pharmaceuticals industries.

Its 12mm stainless steel design and non-wearing sapphire windows make the EXcell 231 a reliable absorption sensor with an integrated digital measurement amplifier. Turbidity values such as EBC / FAU / TEF /mg/I / AU / OD or customer-specific units can be output. The latter can be freely set using the EXpert configuration software.

The sensor can be comfortably parameterised at the PC using the matching EXpert 2.x software and the measuring values can be logged and displayed graphically. Also, a RS485 Modbus interface and an interface for 0...20mA output with an integrated measurement value display are available.

The sensor can be mounted like a standard pH-sensor by its PG13,5 thread connection. The assembly dimensions on the process side are equivalent to those of a standardised sensor. Therefore, this sensor can also be used in combination with retractable process probe housing and fully automatic cleaning systems.



Fig. 5: Sensor EXcell 241

EXcell 241

The NIR absorption sensor EXcell 241 is a high-precision digital NIR rod sensor for monitoring production processes in the biotech, food and pharmaceuticals industries.

Its use on common DN25 welding plugs and the non-wearing sapphire windows make the EXcell 241 a reliable, intelligent absorption sensor with an integrated digital measurement amplifier which is very easy to install on typical industrial fermenters. Turbidity values such as EBC / FAU / TEF / mg/I / AU / OD or customer-specific units can be output. The latter can be freely set using the EXpert configuration software.

The sensor can be comfortably parameterised at the PC using the matching EXpert 2.x software and the measuring values can be logged and displayed graphically. Also, a

RS485 Modbus interface and an interface for 0...20mA output with an integrated measurement value display are available.

The sensor is attached to the welding socket using a G1 1/4" thread. In order to enable the best possible sterile installation, the O-ring-position can be chosen according to the existing plug.

4.1.3 Checking and adjustment

For checking and adjusting reference filters (EXcap 110) with various absorption values, the sensors EXcell 231 and EXcell 241 are available. If necessary, they can be attached to the sensor. To guarantee that inspection/adjustment is carried out without any errors, ensure that the reference filter is placed precisely on the sensor, and that the filter plate is at the lower measuring window of the sensor. The optical sensor unit must be dry and clean for this.



Fig. 6: Reference filter

In order to be able to carry out an inspection or adjustment of the sensor with the reference filter, the unit "AU" must first be selected for the sensor.

NOTE

If the measured value is outside the tolerances of the reference filter and the sensor, recalibration at the manufacturer's side is recommended.

5 Delivery

5.1 Scope of delivery

The sensor is checked at the factory and is shipped ready for installation in packaging which offers the sensor optimal protection.

The delivery includes:

- EXcell sensor
- Certificate for surfaces (optional)
- Certificate for elastomer compound (optional)
- Operating instructions

NOTE

Store the sensor in its packaging. It is best protected there until it is installed.

5.2 Checking the delivery

Before you approve the sensor for assembly, please ensure the following:

- Packaging and device are in good order and condition
- The sensor's identification plate corresponds with the information in the purchase order (→ Chapter 3.6 "Identification plate")

In case of queries, please contact your dealer directly.

6 Assembly

6.1 Assembly

Requirements:

- Sufficient working space is available to operate the sensor.
- The process is deactivated.
- The tanks and pipes are depressurised, empty and clean.
- The connecting piece and the process connector fit together.
- The earthing contact / shield for the connector cable is connected.

6.2 Mechanical connection

ATTENTION

Risk of injury due to escaping process liquid!



Depending on the process liquid's properties, you may incur scalding or chemical skin burns.

Check that the tanks or pipes to which the sensor is being connected is depressurised, empty and clean!

NOTE

Ensure that

- » sufficient working space is available to operate the sensor.
- » the process is switched off.
- » the tanks or pipes are depressurised, empty and clean.
- » the connecting piece and the sensor's process connector fit together.
- » Insert the sensor into the matching process connector.
- Tighten the pressure screw (1) or union nut (1) to a max. of 10-20 Nm. In case of application of the union nut in combination with strong vibrations in the system, the additional use of the safety bracket is recommended (see accessories).



Fig. 7: Union nut / pressure screw at the sensor

NOTE

The red dot on the connector of the sensor can be used as an alignment aid, since it is aligned with the measuring gap.

6.3 Electrical connection ECI-01

NOTE

Ensure that an original cable with the correct connectors is used.

The ECI-01 Exner Communication Interface transfers the measured values of the optical EXcell sensors to a standardised USB 2.0 interface and supplies the required voltage to the sensor.

NOTE

ECI-01 and the EXpert software are required to parameterise the sensor.

Cabinet:	Stainless steel
Voltage supply:	5 V DC via USB interface
Connection:	Fischer Core series / USB connector

6.4 Electrical connection ECI-02

The Exner Communication Interface ECI-02 is used for galvanic isolation of the power supply and the sensor signals. This interface is preferably used when several sensors are used at the same time. The ECI-02 ensures the safe transfer of the Modbus signal to a standardised RS485 interface and an optimal power supply for the connected sensor.

Cabinet	23 mm top-hat rail cabinet
Voltage supply	24 V DC, 1236 V
Output	Modbus RS485
Input	EXcell sensor



ECI-02 terminal diagram



» To terminate RS485, place a jumper between "Terminate 1" and "Terminate 2".

6.5 Electrical connection ECI-03

The ECI-03 Exner Communication Interface transfers the measured values of the optical EXcell sensors to a standardised 0/4...20 mA interface and supplies the required voltage to the sensor.

In addition, a limit value contact and an alarm contact can be used and the colour touch display shows current measured values and parameterisations.



A corresponding connection cable for software updates is provided as an accessory.

6 Assembly

Cabinet:	Panel mounting 48x96 m	m
Voltage supply:	24 V DC	1236 V
Output:	0/420 mA	max. 24 mA
	Limit contact	24V, 100 mA PNP
	Alarm contact	24 V, 100 mA PNP
Input:	EXcell sensor	Terminals
Display:	Graphics	25x29 mm touch function colour

ECI-03 terminal connection diagram

Sensor	r			Current Output	Digital I/O			Current Supply	ľ	Programming	
ш RS 485	- Sensor DC	FE	FE	 Current output (active) 	 Digital IN 24VDC 	 Digital OUT level (24V max 100mA) 	 Digital OUT fault (24V max 100mA) 	- 24 VDC in	FE	FE	ш RS 485
B1	B2	B3	A1	A2	A3	A4	A5	A6	A7	A8	A9
B11	B12	B13	A11	A12	A13	A14	A15	A16	A17	A18	A19
A	+	FE	FE	+	+	+	+	+	FE	FE	A

6.6 Electrical connection EXcell connection cable

The connection cable has an open cable end via which the sensors of the EXcell series can be connected to various communication interfaces and systems.

NOTE

Make sure you are using an original cable with the correct connector.

ATTENTION		
	Risk of i	njury from electric shock!
	»	Pay attention to the correct insulation of exposed contact points.
	»	Do not touch any live components or switch them of before- hand.

The EXcell sensor can be operated with a voltage of 9...24 V DC. It must be ensured that both, the shield of the connection cable and the negative pole of the power supply unit, which is required for the power supply, are connected to the functional earth. In addition to the standard version (...D0) of the sensor, another version (...DA) with an additional analogue output (4-20 mA) and an adjustment input is available.



When using the optionally available analogue output, the sensor can be adjusted to detect recurring product states. The switching input required for this (adjustment input) can be connected via the yellow strand of the connection cable (see above wiring diagram) can be connected.

6 Assembly

Proceed:

- Fasten the sensor in such a way that at least the complete optical assembly is in the desired reference medium. Make sure that there are as few air bubbles in the medium as possible, which could interfere with the measurement results.
- 2. As soon as the measured value has stabilized, the measured value can be set to "0" by applying a 24 V DC switching signal to the adjustment input. In order to activate this offset and to set the value of the reference liquid as "zero value" at the same time, the switching input must be subjected to the specified voltage for approx. 5 seconds.

If the voltage (24 V DC) is only applied to the adjustment input for approx. 1 second, the offset can be activated or deactivated. A "zeroing" does not take place.

NOTE

An electrical voltage must not be applied permanently to the adjustment input (yellow wire) or when the cable is connected. The adjustment input must be kept voltage-free. It is only short-term for the described switching processes with a voltage (24 V DC) to apply

6.7 Electrical connection Lucullus

For the NIR absorption sensors EXcell 231 and EXcell 241 a suitable adapter cable is available especially for connection to a Lucullus system. This optionally can be ordered as an accessory.



Fig. 8: Lucullus system EXcell 231/241 connection cable

	d-sub connector 9	pin female
	ڡ ⁺ ڡ [*] ڡ' ڡ' ڡ۠ۿٙڡ	°O Ŏ
6	DC +	
ΠЪ	DC -	
l S	RS485-A	
缶	RS485-B	
ျပ	Shield/Ground	

7 Parameterisation

WARNING



Setting parameters incorrectly can result in incorrect measurement values and switching points being output. This can have an unwanted impact on processes.

NOTE

Ensure that only authorised and trained staff make changes to the parameterisation.

Use the EXpert 2.x software to parameterise the EXcell sensor. To do this, you must install the Expert 2.x software first on a Microsoft Windows PC with Windows 7 or higher and after that connect the sensor with the ECI 01 communication interface to the USB interface of the PC.

NOTE

Ensure that you

- First install the EXpert 2.x software on the PC and only after successful installation connect the sensor to the computer via the USB interface.
- Are using the latest EXpert 2.x software and the corresponding firmware has been installed on the sensor
- Follow the EXpert 2.x software operating instructions (display by pressing the "F1" key when the software has already started)

7.1 User menu ECI-03



1. You can access the menu by touching the display.



2. You can access the individual parameters as well as the sensor and display data by pressing the arrow symbol. If you want to configure a parameter, touch the tool symbol.



3. Then select the appropriate setting using the arrow keys and confirm by pressing the enter symbol.

7 Parameterisation



- 4. The desired value is also selected using the arrow keys. If a numerical value is set, it can be increased/decreased by one digit by briefly touching the respective arrow key. Keeping the arrow key pressed longer changes the numerical value by increments of 10.
- 5. Press the enter symbol to confirm the value entered and exit this setting level. If no value has been changed and you wish to leave the setting menu level, press the ESC symbol.
- 6. You can return to the readout display by touching the speedo symbol or automatically if no entries have been made or if the display is not touched within a period of 30 seconds.



User menu

The values in **bold** and underlined values are the **standard user parameters**.

Parameter	Name	Value range	Description
Offset	Offset activation	OFF , ON	Activates/deactivates the setting "Offset"
Offset Val	Offset	-6.0 0.0 (for unit AU)	Defines the offset value. A reliable offset value can only be set if the current measured value does not change or only minimally changes over a period of approx. 5 seconds.
Unit	Display toggling	AU , FAU, TEF, EBC, mg/l, CDU	Determines which measurement value should be displayed: CDU : customer-defined unit To adjust the CDU value settings, use the EXpert software.
AO min	Lower output limit (analogue output min)	0.0 6.0 (for unit AU)	Defines the absorption value at which the minimum output current is emitted.
AO max	Upper output limit (analogue output max)	0.0 6.0 (for unit AU)	Defines the absorption value at which the maximum output current is emitted.

Damping	Damping (Damping)	0 100	Dampens the absorption measurement values by outputting a moving average across a set number of measurement values.
DO ON	Switch-on point (digital output on)	0.0 6.0 (for unit AU)	Defines the point at which the digital output is switched on
DO OFF	Disconnection point (digital output off)	0.0 6.0 (for unit AU)	Defines the point at which the digital output is switched off.
DO funct	Switch function (digital output type)	NO , NC	NO = Closer NC = Opener
DO Delay	Switching delay Digital Output delay	0 200 s	Delays the digital output switch by up to 200 seconds.
Language	Language settings	German, English, French, Dutch	Defines the display language.

8 Modbus Register

Modbus communication

Implementation class					
parameter	options				
addressing	1 to 247 (default 1)				
broadcast support	No				
baud rate	1200				
	2400				
	4800				
	9600				
	19200 (default)				
	38400				
	57600				
	115200				
transmission mode	RTU (fixed)				
data bits	8 (fixed)				
parity	none, odd, even, mark, space				
stop bits	1 (fixed)				
electrical interface	RS485 2 Wire cabling				

	Supported Modbus functions
Read Holding Registers (03)	
Write Single Register (06)	
White single Register (06)	

Supported Modbus exeptions

Illegal funktion (01)

Illegal data address (02)

Modbus registers											
Parameter name	Defau lt (deci mal)	Unit	Vari- able type	Range (decimal)	Access	Modbus Address	Description				
4000140070 Readings											
Calibrated AU value		AU x 1000	SWord	-3276832767	Read	40001					
OD value		1000 x	SWord	-3276832767	Read	40002					
Temperature of process		°C x 10	SWord	-3276832767	Read	40003					
Value of Current output		uA	Word	065535	Read	40004					
Current digital output state		#	Word	0/1	Read	40005					
EBC value		EBC	SWord	-3276832767	Read	40006					
CDU value		CDU	SWord	-3276832767	Read	40007	Name is determined by register 254258, The CDU UnitFactor is determined by register 253				
Current acces level		#	Word	065535	Read	40008					
FAU value		FAU x 0.1	SWord	-3276832767	Read	40009					
TEF value		TEF x 0.1	SWord	-3276832767	Read	40010					
mg/l		mg/l x 0.1	SWord	-3276832767	Read	40011					

						contains 100 x
perc (%)	perc x 100	SWord	-3276832767	Read	40012	percentage of max AU
						Standard
						Deviation of the
						current unit
						the unit and factor
Sensor	curre					is that of
Standard	nt Lloit	SWord	20769 20767	Pood	40014	the current
deviation	 AU x	30010	-5270052707	Neau	40014	unit
Raw AU value	1000	SWord	-3276832767	Read	40016	
Error Word	#	Word	065535	Read	40022	bit 0 EEPROM
						Communic
						ation error $(1 - active)$
						(i = active) bit 1
						AU
						Calibration
						error (1 = active)
						bit 2
						EBC
						Calibration
						(1 = active)
						bit 3
						CDU
						error
						(1 = active)
						bit 4
						Overtemp
						(1 = active)

			bit 5
			Led
			Current out
			of limits
			(1 - active)
			(1 - active)
			bit 6
			Led voltage
			out of limits
			(1 = active)
			bit 7
			reserved
			hit 8
			Pof 2 0V
			Fror
			(1 octivo)
			(1 = active)
			DIT 9
			Ref 4.1V
			Error
			(1 = active)
			bit 10
			SupplyVolt
			age 5.0
			Error
			(1 = active)
			bit 11
			PCB
			OVertemp
			(1 = active)
			hit 12
			(S)Word
			(J) VVOI U
			(1 octive)
			(1 = aCTIVe)
			bit 13
			Invalid
			Zeropoint/I
			nvalid
			pathlength
			(1 = active)
			bit 14
			reserved
			bit 15
			reserved

Warning Word	#	Word	065535	Read	40023	bit 0
- 5						Low signal
						LOW SIGNAL
						bit 1
						reserved
						10001100
						bit 2
						reserved
						1.11.0
						DIT 3
						reserved
						hit 1
						reserved
						bit 5
						received
						I Cochived
						bit 6
						reserved
						hit 7
						reserved
						bit 8
						reserved
						reserved
						bit 9
						reserved
						bit 10
						DIL IU
						reserved
						hit 11
						record
						reserved
						bit 12
						reserved
						1.1.10
						bit 13
						reserved
						bit 14
						DIL 14
1		1		1		reserved

							bit 15
							reserved
							contains
							1000 x AU
		AU x					Offset
AUOffset	0	1000	SWord	-3276832767	Read	40025	value
							contains
							the through
							calibration
							tables
							calculated
FDCOffeet	0	FDC	Current	22760 22767	Deed	40000	EBC Offset
EBCOffset	0	ERC	Sword	-32/6832/6/	Read	40026	value
							contains
							calibration
							tables
							calculated
CDUOffset	0	CDU	SWord	-32768 32767	Read	40027	value
		000	511010	5270052707	nedd	10021	contains
							the through
							calibration
							tables
							calculated
		OD x					OD offset
ODOffset	0	1000	SWord	-3276832767	Read	40028	value
							contains
							the through
							calibration
							tables
							calculated
		FAU x					FAU offset
FAUOffset	0	0.1	SWord	-3276832767	Read	40029	value
							contains
							the through
							calibration
							tables
		TEE					
TEEOffeet	0		CMard	22760 22767	Dood	40020	TEF Offset
TEFUTSEL	0	U.1	2 AA OLO	-32/0032/0/	кеаа	40030	value

mg_lOffset	0	mg/l > 0.1	< SWord	-3276832767	Read	40031	contains the through calibration tables calculated mg_l offset value
percOffset	0	perc × 100	sWord	-3276832767	Read	40032	contains the through calibration tables calculated perc offset value
Parameter name	Defau It (deci mal)	Unit	Variable type	Range (decimal)	Access	Modbus Address	Description
			4007	140300 Settings	;		
Modbus slave adres	1	#	Word	1247	Read/ Service	40071	
Modbus baudrate	1920	#	Word	120/240/480/ 960/1920/384 0/ 5760	Read/ Service	40072	Value = baudrate/1 0
Modbus Parity	0		Word	0, 1, 2, 3, 4	Read/ Service	40073	Parity 0 = none, 1 = odd, 2 = even, 3 = mark, 4 = space
Averaging number	5	#	Word	02000	Read/ Service	40076	Smoothing factor for averaging (Running average) (0 -> AVG = RAW)

r	1	r					
							Window
							size of
							filtering
							and
							avaraging
							colculation
C 511 AV					D 1/		Calculation
SensorFilterAV					Read/		(Noice
Gnr	5		Word	5,,,100	Service	40077	reduction)
							Smoothing
							factor for
							averaging
							Temperatur
							e value
Temp					Read/		(0 -> AVG
averaging pr	5	#	Word	0 20	Service	40078	- PAMA
averaging m	J	π	word	020	Service	40070	- 1(AVV)
							$0 - \Delta U$
							0 – AU, 1 – FRC
							I = EDC,
							2 =CDU,
							3 = OD,
							4 = TEF,
							5 = FAU,
					Read/		6 = mg/l,
Active unit	1	#	Word	0/1/2/3/4/5/6	Service	40079	7 = perc
							Value
							should be
							given in
							current
							Active Unit
		Acti					(dotormino
D' ILL L		ACU			D. II		(determine
Digital output	4	ve	C 1	20760 20767	Read/	10000	a in register
UN Level	1	Unit	Sword	-32/6832/6/	Service	40080	40079)
							Value
							should be
							given in
							current
							Active Unit
		Acti					(determine
Digital output		VA			Read/		d in register
	2	l Init	Sword	-32768 32767	Service	40081	40070)
UT LEVEI	۷.	UTIL	SWULU	-3210032101	JEIVICE	40001	40073)
Digital output					Pood/		0 = Closor
function	0	ш	14/	0./1	Redu/	40000	
Tunction	U	#	word	U/ I	Service	40082	i = Opener

		505					
Digital output		sec			Deed/		
		ona			Read/	10000	
delay	0	S	Word	0200	Service	40083	
							0 = normal
							operation,
Digital output					Read/		1 = inverted
inverted	0	#	Word	0/1	Service	40084	operation
							0 = 0-
							20mA.
Current loop					Read/		1 = 4 -
mode	1	#	Word	0/1	Service	40085	20mΔ
mode		"	word	0/1	Service	40005	Currentlee
							Currentioo
							p value
							belonging
							to 0 or 4
							mA, Value
							should be
							given in
							current
							Active Unit
		Acti					(determine
Current loop		ve			Read/		d in register
min value	0	Unit	Sword	-3276832767	Service	40086	40079)
							Currentloo
							p value
							belonaina
							to 20mA.
							Value
							should be
							given in
							given in
		A+:					(determine
Commenting		ACTI			Deed		(determine
Current loop		ve	C 1	20762 20767	Read/	10007	d in register
max value	8	Unit	Sword	-32/6832/6/	Service	40087	40079)
							Closed
							Loop
							output
							current
							when
Current loop					Read/		sensor in
failure value	0	uA	Sword	-3276832767	Service	40088	error

							Contains the Value of the Active Unit @ "MaxAUAla rm" Or if that's
							impossible, the
May Active		Acti					maximum
Unit Value		ve Unit	Sword	-3276832767	Read	40089	(32767)
		Acti					Contains the Value of the Active Unit @ "AU = 0" Or if that's impossible, the minimum
Min Active		ve Lloit	Sword	-30768 30767	Pead	10090	value (-32768)
OffsetStatus	0	#	word	0/1	FREE	40090	Setting this value To zero = 'offset off', Setting this value to any other value = 'offset on'
Viewsettings	0	#	Word	065535	Read/	40092	bit 0
					Service		if true, Present 1 digit more in LCD and PC Software

			bit 1 if true noise reduction via STDev and averaging is on, else no noise reduction (This is different from the
			running averaging!) bit 2
			reserved bit 3 reserved
			bit 4 reserved
			bit 6
			bit 7 reserved
			bit 8 reserved bit 9
			reserved bit 10 reserved
			bit 11 reserved

							bit 12
							reserved
							bit 13
							reserved
							bit 14
							reserved
							bit 15
							reserved
							Setting this
							address to
							the value in
							address
							299 to get
							access for
Temp Access							one
Code	0	#	word	0 65535	FRFF	40098	operation
	-						Setting this
							register To
							other than
							zero
							triggers a
							recalculatio
							n of the
							offsetvalues
							with the
	_						current
OffsetZero	0	#	word	0/1	FREE	40099	calibrated
							offsetless
							AU Value
							register is
							Reset To 0
							after
							executing a
							command

							If this
							register is
							Set $(<>0)$
							Then
							Calibration
							slopes are
							recalculate
							d And the
							register is
Recalcalculate	0	#	word	065535	Read	40100	Reset
							Pathlength
							between
							LED and
							Sensor
Path length	5000	μm		1000 - 65535	Read	40125	(um)
							Is also
LED switch							overtemp
OFF		10 x					trigger
temperature	900	°C	Word	500 - 2500	Read	40126	value
							example 1:
							-1 = CDU x
							0,1
							example 2:
CDU					Read/		3 = CDU x
UnitFactor	0		SWord	-33	Service	40254	1000
CDU unit	CDU		String 10		Read/		low-byte;
name			Chars		Service		Char 1
							(most left
						40255	position)
							high-byte;
							Char 2
							low-byte;
						40256	Char 3
							high-byte;
							Char 4
							low-byte;
						40257	Char 5
							high-byte;
							Char 6
							low-byte;
						40258	Char 7
							high-byte;
							Char 8

r							
						10250	low-byte;
						40259	high-byte
							Char 10
							(most right
							position)
							Code to
							enter in 97
							to get
							Sevicelevel
					5 1/6		access for
Service Level	122.45	ш		0 (5525	Read/Serv	40200	one
Access Code	12345	#	word	065535	ice	40300	operation
	Defau						
	lt						
Parameter	(deci	1.1	Variable	Range	A	Modbus	Deservitetiere
name	mal)	Unit	туре	(decimal)	Access	Address	Description
	1	4030	<mark>0140400 Se</mark>	nsor Software/Ha	ardware data		
Manu-			String (10	ASCII	Read		low-byte;
facturer ID			Chars)				Char 1
						40205	(most left
				-		40306	position)
							Char 2
							low-byte,
						40307	Char 3
							high-byte,
							Char4
						10208	low-byte; Char 5
						40300	high-byte:
							Char 6
							low-byte;
						40309	Chart 7
							high-byte;
							Char 8
						10210	low-byte;
						40310	Chart 9
							nigh-byte;
							(most right
							nosition)
	1	1	1	1	1	1	posicion

Reseller ID		String (10 Chars)	ASCII	Read		low-byte; Char 1
						(most left
					40311	position)
						high-byte.
						Char 2
						low-byte,
					40312	Char 3
						high-byte,
						Char4
						low-byte;
					40313	Char 5
						high-byte;
						Char 6
						low-bvte;
					40314	Chart 7
						high-byte;
						Char 8
						low-byte;
					40315	Chart 9
						high-byte;
						Char 10
						(most right
						position)
Sensor ID		String (10	ASCII	Read		low-byte;
		Chars)				Char 1
						(most left
					40316	position)
						high-byte,
						Char 2
						low-byte,
					40317	Char 3
						high-byte,
						Char4
						low-byte;
					40318	Char 5
						high-byte;
						Char 6
						low-byte;
					40319	Chart 7
						high-byte;
						Char 8
						low-byte;
					40320	Chart 9

						high-byte;
						Char 10
						(most right
						position)
Firmware		String (10	ASCII	Read		low-byte;
version		Chars)				Char 1
						(most left
					40321	position)
						high-byte,
						Char 2
						low-byte,
					40322	Char 3
						high-byte,
						Char4
						low-byte;
					40323	Char 5
						high-byte;
						Char 6
						low-byte;
					40324	Chart 7
						high-byte;
						Char 8
						low-byte;
					40325	Chart 9
						high-byte;
						Char 10
						(most right
						position)
Sensor serial		String (30	ASCII	Read		low-byte;
number		Chars)				Char 1
						(most left
					40336	position)
						high-byte,
						Char 2
						low-byte,
					40337	Char 3
						high-byte,
						Char4
						low-byte;
					40338	Char 5
						high-byte;
						Char 6
	1					low-byte;
					40339	Chart 7

				1.5.1.1.1.1.
				nign-byte;
				Char 8
				low-byte;
			40340	Chart 9
				high-byte;
				Char 10
				low-byte:
			40341	Char 11
				high-byte
				Char 12
				low bute:
			10212	Char 12
			40342	
				nign-byte;
				Char 14
				low-byte;
			40343	Char 15
				high-byte;
				Char 16
				low-byte;
			40344	Chart 17
				hiah-bvte;
				Char 18
				low-byte:
			40345	Char 19
			-105-15	high byte:
				Char 20
			10246	IOW-Dyte,
			40340	
				nign-byte;
	-			Char 22
				low-byte;
 	ļ		40347	Char 23
				high-byte;
				Char 24
				low-byte;
			40348	Char 25
				high-byte;
				Char 26
				low-byte;
			40349	Char 27
				high-byte
				Char 28
				low-byte:
			10250	Char 20
			40300	Char 29

						high-byte;
						Char 30
						(most right
						position)
Sensor type		String (30	ASCII	Read		low-byte;
number		Chars)				Char 1
						(most left
					40351	position)
						high-byte,
						Char 2
						low-byte,
					40352	Char 3
						high-byte,
						Char4
						low-byte;
					40353	Char 5
						high-byte;
						Char 6
						low-byte;
					40354	Chart 7
						high-byte;
						Char 8
						low-byte;
					40355	Chart 9
						high-byte;
						Char 10
						low-byte;
					40356	Char 11
						high-byte;
						Char 12
						low-byte;
					40357	Char 13
						high-byte;
						Char 14
						low-byte;
					40358	Char 15
						high-byte;
						Char 16
						low-byte;
					40359	Chart 17
						high-byte;
						Char 18
						low-byte;
					40360	Char 19

							high-byte; Char 20
			-				low-byte:
						40361	Char 21
						-10501	bigh byte:
							Char 22
						10262	iow-byte,
						40362	Char 23
							high-byte;
							Char 24
							low-byte;
						40363	Char 25
							high-byte;
							Char 26
							low-byte;
						40364	Char 27
							high-byte;
							Char 28
							low-byte;
						40365	Char 29
							high-byte;
							Char 30
							(most right
							position)
Sensor tag			String (30	ASCII	Read/Serv		low-byte:
number			Chars)		ice		Char 1
			,				(most left
						40366	nosition)
						10000	high-hyte
							Char 2
							low-byte
						40367	Char 3
						10001	high-hyte
							Char/
						10369	Char 5
						40300	
							nign-byte;
						40260	iow-byte;
						40369	
							nign-byte;
							Char 8
							low-byte;
1	1			1		40370	Chart 9

				high-byte;
				Char 10
				low-byte;
			40371	Char 11
				high-byte;
				Char 12
				low-byte;
			40372	Char 13
				high-byte;
				Char 14
				low-byte;
			40373	Char 15
				high-byte;
				Char 16
				low-byte;
			40374	Chart 17
				high-byte;
				Char 18
				low-byte;
			40375	Char 19
				high-byte;
				Char 20
				low-byte;
			40376	Char 21
				high-byte;
				Char 22
				low-byte;
			40377	Char 23
				high-byte;
				Char 24
				low-byte;
			40378	Char 25
				high-byte;
				Char 26
				low-byte;
			40379	Char 27
				high-byte;
				Char 28
				low-byte;
			40380	Char 29
				high-byte;
				Char 30
				(most right
				position)

	Defau										
	lt										
Parameter	(deci		Variable	Range		Modbus					
name	mal)	Unit	type	(decimal)	Access	Address	Description				
	4040140512 Status										
							40401 =				
		sec					low-word				
		ond		0429496729		4040140	40402 =				
Up time		S	DWord	5	Read	402	high-word				
							40403 =				
							low-word				
				0429496729		4040340	40404 =				
Startups		#	DWord	5	Read	404	high-word				
Highest											
proces		°C x									
temperature		10	SWord	-3276732767	Read	40421					
							Level				
							determined				
# Proces							by register				
overtemps		#	Word	065535	Read	40423	125				
							Contains				
							Start				
							register				
							adress of				
Extended							Extended				
Modbus Start							Modbus				
Register	2048	#	Word	065535	Read	40511	array				
							Contains				
							Length of 1				
							unit in				
Extended							Extended				
Modbus Unit							modbus				
Length	16	#	Word	065535	Read	50512	Array				

Extended Modbus registers									
Parameter name	Default (decimal)	Unit	Variable type	Range (decimal)	Access	Modbus Address	Description		
	4204942176 Readings								
Unit 0 Value pointer	0		Word	065535	Read	42049	Pointer to AU value (Register)		
Unit 0 factor	3		SWord	-32767 32767	Read	42050	Factor (3 = AU x 1000)		
Offset Unit 0	0		Word	-32767 32767	Read	42051	AU offset value		
reserved Unit 0			Word	065536	Read	42052			
reserved Unit 0			Word	065537	Read	42053			
Unit 0 reserved			Word	065539	Read	42054			
Unit 0 reserved			Word	065540	Read	42056			
Unit 0 reserved			Word	065541	Read	42057			
Unit 0 reserved			Word	065542	Read	42058			
reserved Unit 0			Word	065543	Read	42059	Unitname		
name Unit 0	UA		ASCII	065544	Read	42060	(Little Endian!) Unitname		
name Unit 0			ASCII	065545	Read	42061	(Little Endian!) Unitname		
name Unit 0			ASCII	065546	Read	42062	(Little Endian!) Unitname		
name Unit 0 name			ASCII	065547	Read Read	42063 42064	(Little Endian!) Unitname (Little Endian!)		
Unit 1 Value pointer	5		Word	065535	Read	42065	Pointer to EBC value (Register)		

Unit 1			-32767			Factor
factor	0	SWord	32767	Read	42066	$(0 = EBC \times 1)$
Unit 1			-32767			
Offset	0	Word	32767	Read	42067	EBC offset value
Unit 1						
reserved		Word	065536	Read	42068	
Unit 1						
reserved		Word	065537	Read	42069	
Unit 1						
reserved		Word	065538	Read	42070	
Unit 1						
reserved		Word	065539	Read	42071	
Unit 1						
reserved		Word	065540	Read	42072	
Unit 1						
reserved		Word	065541	Read	42073	
Unit 1						
reserved		Word	065542	Read	42074	
Unit 1						
reserved		Word	065543	Read	42075	
Unit 1						Unitname
name	BE	ASCII	065544	Read	42076	(Little Endian!)
Unit 1						Unitname
name	С	ASCII	065545	Read	42077	(Little Endian!)
Unit 1						Unitname
name		ASCII	065546	Read	42078	(Little Endian!)
Unit 1						Unitname
name		ASCII	065547	Read	42079	(Little Endian!)
Unit 1						Unitname
name		ASCII	065548	Read	42080	(Little Endian!)
Unit 2						
Value						Pointer to CDU
pointer	6	Word	065535	Read	42081	value (Register)
Unit 2			-32767			Factor
factor	3	SWord	32767	Read	42082	(3 = CDU x 1000)
Unit 2			-32767		100	6011 K
Offset	U	Word	32767	Read	42083	CDU offset value
Unit 2			0.05500		1000	
reserved	$\left \right $	Word	065536	Kead	42084	
Unit 2			0 65507		10005	
reserved	$\left \right $	Word	065537	Kead	42085	
Unit 2					100	
reserved		Word	065538	Read	42086	

		I			1	1
Unit 2 reserved		Word	0 65539	Read	12087	
Linit 2		Word	005555	neau	42007	
reserved		Word	0 65540	Read	42088	
Linit 2		Word	003310	neuu	12000	
reserved		Word	0 65541	Read	42089	
Unit 2		Word	003311	neuu	12005	
reserved		Word	065542	Read	42090	
Unit 2						
reserved		Word	065543	Read	42091	
Unit 2						Unitname
name	DC	ASCII	065544	Read	42092	(Little Endian!)
Unit 2						Unitname
name	U	ASCII	065545	Read	42093	(Little Endian!)
Unit 2						Unitname
name		ASCII	065546	Read	42094	(Little Endian!)
Unit 2						Unitname
name		ASCII	065547	Read	42095	(Little Endian!)
Unit 2						Unitname
name		ASCII	065548	Read	42096	(Little Endian!)
Unit 3						
Value						Pointer to OD
pointer	1	Word	065535	Read	42097	value (Register)
Unit 3	2		-32767		12000	Factor
factor	3	SWord	32767	Read	42098	$(3 = OD \times 1000)$
Unit 3	0		-32/6/	D	12000	
Offset	0	word	32767	Read	42099	OD offset value
Unit 3		Word	0 65526	Dood	42100	
Lipit 2		woru	003350	Reau	42100	
received		Word	0 65537	Read	/2101	
Linit 3		Word	005557	neau	72101	
reserved		Word	0 65538	Read	42102	
Unit 3		Word	003330	neuu	IEIGE	
reserved		Word	065539	Read	42103	
Unit 3						
reserved		Word	065540	Read	42104	
Unit 3						l
reserved		Word	065541	Read	42105	
Unit 3						
reserved		Word	065542	Read	42106	
Unit 3						
reserved		Word	065543	Read	42107	

r	1	1	-		1	
Unit 3		1.5.5%	0 65544		10100	Unitname
name	DO	ASCII	065544	Read	42108	(Little Endian!)
Unit 3						Unitname
name		ASCII	065545	Read	42109	(Little Endian!)
Unit 3						Unitname
name		ASCII	065546	Read	42110	(Little Endian!)
Unit 3						Unitname
name		ASCII	065547	Read	42111	(Little Endian!)
Unit 3						Unitname
name		ASCII	065548	Read	42112	(Little Endian!)
Unit 4						
Value						Pointer to TEF
pointer	9	Word	065535	Read	42113	value (Register)
Unit 4			-32767			Factor
factor	-1	SWord	32767	Read	42114	$(-1 = \text{TEF} \times 0, 1)$
Unit 4			-32767			
Offset	0	Word	32767	Read	42115	TEF offset value
Unit 4						
reserved		Word	065536	Read	42116	
Unit 4						
reserved		Word	065537	Read	42117	
Unit 4						
reserved		Word	065538	Read	42118	
Unit 4						
reserved		Word	065539	Read	42119	
Unit 4						
reserved		Word	065540	Read	42120	
Unit 4						
reserved		Word	065541	Read	42121	
Unit 4						
reserved		Word	065542	Read	42122	
Unit 4						
reserved		Word	065543	Read	42123	
Unit 4						Unitname
name	ET	ASCII	065544	Read	42124	(Little Endian!)
Unit 4						Unitname
name	F	ASCII	065545	Read	42125	(Little Endian!)
Unit 4						Unitname
name		ASCII	065546	Read	42126	(Little Endian!)
Unit 4						Unitname
name		ASCII	065547	Read	42127	(Little Endian!)
Unit 4						Unitname
name		ASCII	065548	Read	42128	(Little Endian!)

Unit 5						
Value						Pointer to FAU
pointer	8	Word	065535	Read	42129	value (Register)
Unit 5			-32767			Factor
factor	-1	SWord	32767	Read	42130	(-1 = FAU x 0,1)
Unit 5			-32767			
Offset	0	Word	32767	Read	42131	FAU offset value
Unit 5						
reserved		Word	065536	Read	42132	
Unit 5						
reserved		Word	065537	Read	42133	
Unit 5						
reserved		Word	065538	Read	42134	
Unit 5						
reserved		Word	065539	Read	42135	
Unit 5						
reserved		Word	065540	Read	42136	
Unit 5						
reserved		Word	065541	Read	42137	
Unit 5						
reserved		Word	065542	Read	42138	
Unit 5			0.05540		10100	
reserved		Word	065543	Read	42139	11.5
Unit 5		A.C.C.II	0 65544	Duri	40140	Unitname
name	AF	ASCII	065544	Read	42140	(Little Endian!)
Unit 5			0 65545	Deed	40141	Unitname
name	U	ASCII	065545	Read	42141	(Little Englan!)
Unit 5			0 65546	Dood	12112	Unitname (Little Endiant)
name	+ +	ASCII	005540	Read	42142	
			0 65547	Pood	10110	(Little Endianl)
Lipit 5		ASCII	005547	Reau	42143	
name			0 65548	Read	12111	(Little Endianl)
Linit 6	+ +	AJCII	003340	neau	72144	
Value						Pointer to ma/l
pointer	10	Word	0 65535	Read	42145	value (Register)
Unit 6	10	, void	-32767	nead	TLITJ	Factor
factor	-1	SWord	32767	Read	42146	$(-1 = m\alpha/l \times 0.1)$
Unit 6		544010	-32767	neuu	12170	(' '''''''''''''''''''''''''''''''''''
Offset	0	Word	32767	Read	42147	mg/Loffset value
Unit 6	Ť					
reserved		Word	065536	Read	42148	
Unit 6	+ +					
reserved		Word	065537	Read	42149	

			1			1
Unit 6 reserved		Word	0 65538	Read	12150	
Linit 6	+ +	word	0055550	neau	42150	
received		Word	0 65530	Pead	/2151	
Lipit 6	1	woru	005555	Reau	42131	
Unit 0		Word	0 65540	Pood	10150	
Lipit 6	1	woru	005540	Reau	42152	
reserved		Word	065541	Read	42153	
Unit 6						
reserved		Word	065542	Read	42154	
Unit 6					-	
reserved		Word	065543	Read	42155	
Unit 6	1					Unitname
name	gm	ASCII	065544	Read	42156	(Little Endian!)
Unit 6						Unitname
name	1/	ASCII	065545	Read	42157	(Little Endian!)
Unit 6						Unitname
name		ASCII	065546	Read	42158	(Little Endian!)
Unit 6						Unitname
name		ASCII	065547	Read	42159	(Little Endian!)
Unit 6						Unitname
name		ASCII	065548	Read	42160	(Little Endian!)
Unit 7						
Value						
pointer	11	Word	065535	Read	42161	Pointer to % value
Unit 7			-32767			Factor
factor	2	SWord	32767	Read	42162	(2 = % x 100)
Unit 7			-32767			
Offset	0	Word	32767	Read	42163	% offset value
Unit 7						
reserved		Word	065536	Read	42164	
Unit 7						
reserved		Word	065537	Read	42165	
Unit 7						
reserved		Word	065538	Read	42166	
Unit 7						
reserved		Word	065539	Read	42167	
Unit 7						
reserved		Word	065540	Read	42168	
Unit 7						
reserved		Word	065541	Read	42169	
Unit 7						
reserved		Word	065542	Read	42170	

Unit 7 reserved		Woi	d 065543	3 Read	42171	
Unit 7 name	%	ASC	06554	4 Read	42172	Unitname (Little Endian!)
Unit 7						Unitname
name		ASC	06554	5 Read	42173	(Little Endian!)
Unit 7						Unitname
name		ASC	065546	5 Read	42174	(Little Endian!)
Unit 7						Unitname
name		ASC	06554	7 Read	42175	(Little Endian!)
Unit 7						Unitname
name		ASC	065548	B Read	42176	(Little Endian!)

9 Maintenance

9.1 Important maintenance notes

- Service the sensor regularly Prepare a maintenance schedule for the respective process.
- Only trained personnel is allowed to perform maintenance work.
- Always wear appropriate protective clothing when performing maintenance works.
- Only perform maintenance work or repairs described in the operating manual.
- Changes to the design may only be carried out after consulting with the manufacturer.
- Pipes or tanks must be depressurised, empty and clean before you remove the sensor from the process.

9.2 Checking the process connector

The sensor is held and sealed in the connector by the pressure screw (1).

NOTE

Check regularly whether the process connector is sealed. If necessary, tighten the pressure screw (1) or the union nut (1) to 10-20 Nm.



Fig. 9: Union nut / pressure screw at the sensor

9.3 Clean the measurement window

Absorption in the process is measured by two measurement windows (sapphire). The measurement value can be distorted by contaminants or deposits.

Clean deposits from the measurement window regularly.

- 1. Remove the sensor from the process connector.
- 2. Remove deposits from the windows.
- 3. Check the measuring window for possible damage.

ATTENTION

Risk of injury due to escaping process liquid!



- » Wear safety goggles and protective clothing!
- Check that the tanks or pipe the sensor is being connected to is/are depressurised, empty and clean!



Fig. 10: Measurement window on the sensor

9.4 Autoclaving

- Observe the pressure temperature diagram (\rightarrow Chapter 3.5)
- Disconnect the sensor from all electronic components
- Protect the LED against the influence of high temperatures and select the autoclaving times as short as possible
- Equip the connector plug with the protection cap.

NOTE

Temperatures above 90 $^{\circ}$ C significantly reduce the life of the LED. Protect the LED by de-energising the sensor during sterilisation or autoclaving and keeping process times as short as possible.

9.5 Maintenance plan

Perform the maintenance work at recommended intervals!

Interval	Work
Every three	Visually check the tightness of the process connector.
months	Tighten the pressure screw to a maximum of 10-20 Nm.
Yearly	Remove the sensor and clean the measurement window.

Adjust the intervals for required maintenance to suit your process conditions.

10 Ordering structure

10.1 EXcell 231 sensor

	Code	Measure	ement rar	nge				
	С	06 AU	/ 06600) EBC / 01	2 OD			
	Х	Special	version					
		Code	Shaft le	ngth				
		120	120 mm	1				
		225	225 mn	٦				
		325	325 mn	า				
		425	425 mm Special version					
		XXX						
			Code Optical path length					
			05	5 mm				
			10	10 mm				
			20	20 mm				
			XX	Special ve	ersion			
				Code	Process	s connection		
				PG1	Gewind	de PG 13,5		
				XXX	Special	version		
					Code	Interface		
				D0 Modbus RTU (RS485) DA Modbus RTU (RS485) / 420 m				
EXcell 231						Ordercode		

Example: EXcell 231-C-225-10-PG1-D0

10.2 Sensor EXcell 241

	Code	Measure	ement ra	nge				
	С	06 AU	/ 0660	0 EBC / 0	12 OD			
	Х	Special	version					
		Code	Immers	sion lengt	th			
		070	65 mm	+ optica	l path ler	ngth		
		110	105 mn	n + optic	al path le	ngth		
		XXX	XXX Special version					
			Code Optical path length					
			05	5 mm				
			10	10 mm				
			20	20 mm				
			XX	Special	version			
				Code O-Ring position				
				25	25 mm			
				28	28 mm			
				29	29 mm			
				30	30 mm	(for sta	ndard weld-in socket)	
				35	35 mm			
				50	50 mm			
				55	55 mm			
				XX	Special	version	I	
					Code	Sealin	g material	
					EPD	EPDN	1 (FDA/USP VI)	
					XXX Special version			
				Code Interface				
						D0	Modbus RTU (RS485)	
						DA	Modbus RTU (RS485) / 420 mA	
EXcell 241							Ordercode	

Example: EXcell 241-C-110-05-30-EPD-D0

11 Spare parts and accessories

EXcell 231 / 241 accessories	Order code
PC EXpert 2.x software on a USB stick (for Windows)	2-120-69-003
Communication interface ECI-01 for PC connection via USB	2-120-69-004
Communication interface ECI-02 Modbus RS485	2-120-58-003
Communication interface ECI-03 020mA with display	2-120-69-005
EXcell 231/241 2m connection cable (for ECI-02/03)	2-120-69-001
EXcell 231/241 5m connection cable (for ECI-02/03)	2-120-69-002
EXcell 231/241 2m connection cable (for Lucullus)	2-120-69-006
EXcell 231/241 5m connection cable (for Lucullus)	2-120-69-007
Connection cable ECI-01 to ECI-03	2-120-69-009

Accessories for EXcell 241	Order code
Safety weld-in socket DN25 straight, 40 mm, 1.4404 / 316L	2-087-33-001
Safety weld-in socket DN25 inclined, 40 mm, 1.4404 / 316L	2-087-33-002
Safety bracket SK25 for welding socket DN25 (Ingold)	2-140-33-002

EXcell 231 / 241 certificates	Order code
Certificate EN10204-2.2 for surface-finishing (Ra<0,37 $\mu\text{m})$	2-121-01-019
Certificate EN10204-3.1 for materials (media wetted parts)	2-121-01-002
Certificate for elastomer-compound EPDM-FDA / USP VI according to DIN EN 10204-2.2	2-121-01-003
Certificate for factory calibration NIR sensors acc. DIN EN 10204-3.1	2-121-01-022

EXcell 231 / 241 factory inspection	Order code
Factory recalibration for NIR sensors incl. certificate	2-999-00-013
(proof of return)	

12 Disposal

Please observe the valid rules and regulations concerning disposal in the country and at the place of application.

Disposal

Ensure that the sensor is free from hazardous and toxic substances. Components must be disposed of separately in accordance with their respective materials.

Packaging

The packaging consists of cardboard and can be disposed of with scrap paper. The integrated foam inserts must be removed in advance.

13 Certificates and compliances

All freely available certificates and conformities can be found in their most current form in the "Downloads" section of our website.

To access the following address, enter it into your browser or scan the QR code below. Then select the relevant product and document from the list.

https://e-p-e.com/en/downloads



Depending on the product, additional certificates (e.g. material, surface, etc.) are available. If necessary, please send a corresponding request to Exner Process Equipment GmbH.



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